

# TUBULAR MOTOR BUILD-IN RECEIVER AND ELECTRONIC LIMIT SETTING

### **TECHNICAL SPECIFICATION:**

Part no: 3416600112 3416600116 3416600117 Torque: 6Nm 13Nm 6Nm Speed: 14rpm 28rpm 20rpm 230Vac - 50Hz 230Vac - 50Hz 230Vac - 50Hz Voltage:

Power/Watt:121W121W133WProtection degree:IP44IP44IP44

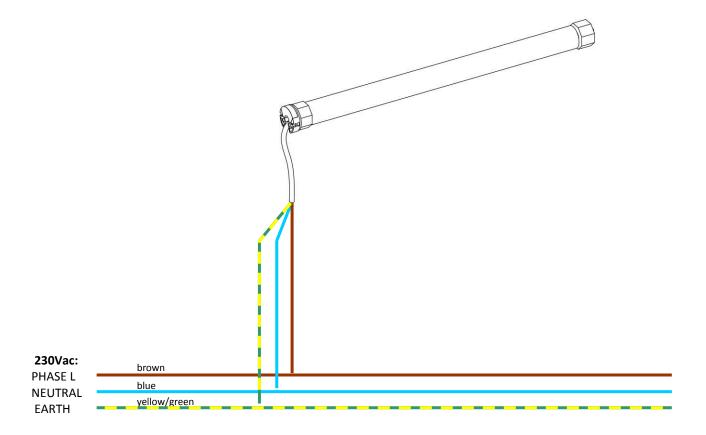
Max. running time 4 minutes

## **IMPORTANT**



230V: use only wires BROWN (phase), BLUE (neutral) and GREEN/YELLOW (earth).

The additional two wires (thin wire, black and red) are for connecting the optional obstruction sensor. Make sure these two wires are not connected together and do NOT make contact with the power wires.





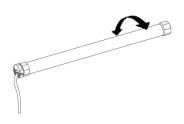
## TUBULAR MOTOR BUILD-IN RECEIVER AND ELECTRONIC LIMIT SETTING

PROGRAMMING REMOTE TO TUBULAR MOTOR:

ADD MORE REMOTES OR CHANNELS TO TUBULAR MOTOR

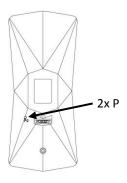
**CANCEL ALL REMOTES** 

press button on motor, motor will turn short to acknowledge

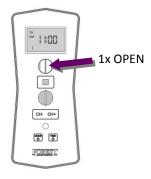


within 6 seconds:

press P button two times



press OPEN button one time



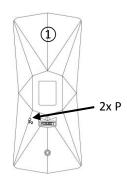
motor will turn to acknowledge



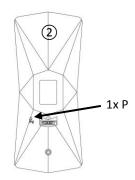
**CHANGING DIRECTION OF ROTATION:** 

To change the direction of rotation, keep green button on motor pressed for 7 sec, until motor turns to acknowledge.

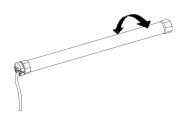
<u>1</u>st remote: press P button two times



2)nd remote: press P button one time

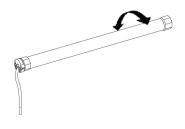


motor will turn to acknowledge

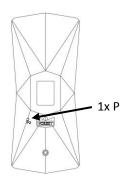


to add another channel: 1.press 2xP button of programmed channel, 2.select other channel and press P button

motor will turn to acknowledge



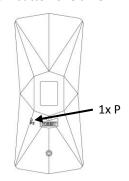
press P button one time



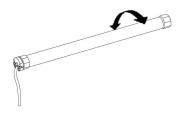
press STOP button one time



press P button one time



motor will turn to acknowledge





## **TUBULAR MOTOR**

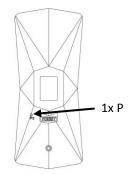
## **BUILD IN MULTI RECEIVER AND ELECTRONIC LIMIT SETTING**

### **ADJUSTING UPPER AND LOWER END LIMITS:**



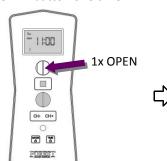
- when multiple motors are programmed to one channel, end limits of all motors will be adjusted
- during programming, keep the remote within 2 mtr from the motor

press P button one time

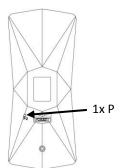




press OPEN button one time



press P button one time



press STOP button when required

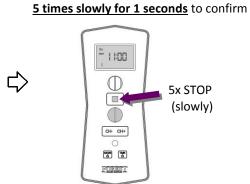
height is reached. Press STOP button

motor will turn to acknowledge

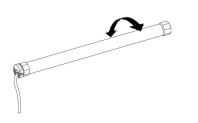


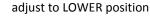
adjust to UPPER position

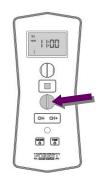




motor will turn to acknowledge



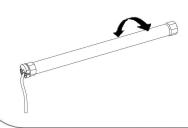




press STOP button when required height is reached. Press STOP button 5 times slowly for 1 seconds to confirm



motor will turn to acknowledge, limits have been set successfully.





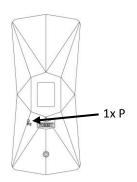
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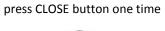
## **CANCELLATION OF UPPER AND LOWER END LIMITS:**

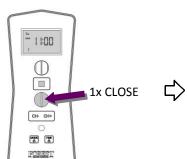


IMPORTANT: When cancelling end limits, the limits of all motors, programmed to selected channel, will be cancelled

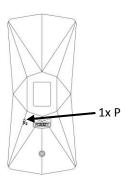
press P button one time







press P button one time



motor will turn to acknowledge

